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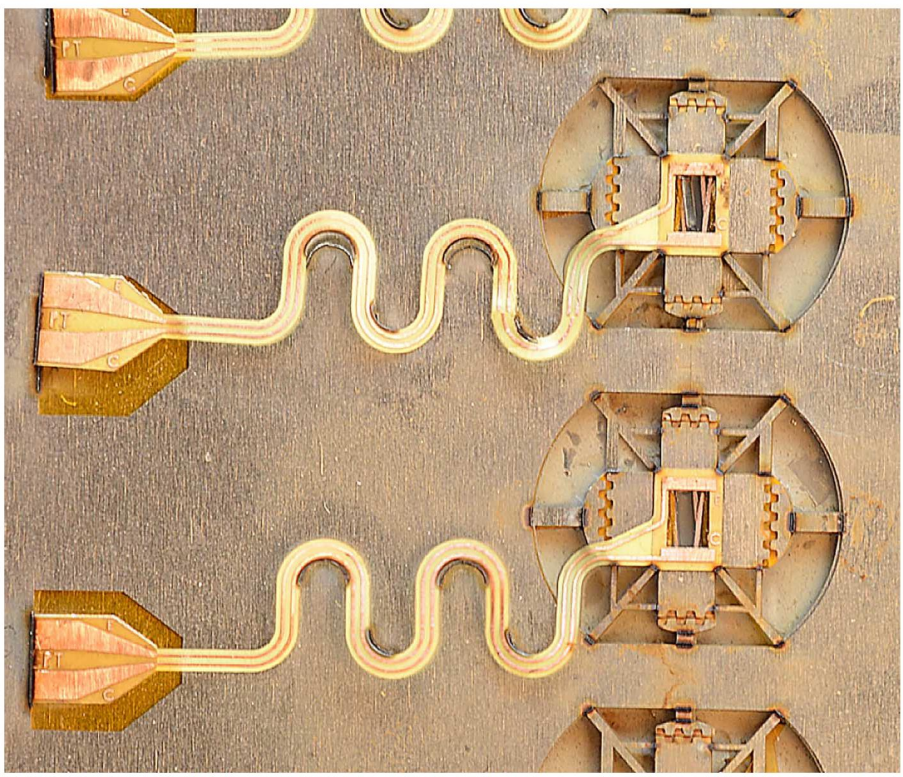

Batch fabricated mm-scale force sensors, suitable for surgical robots, prior to release and self-assembly into the final 3D shape.

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