

# IEEE SENSORS JOURNAL

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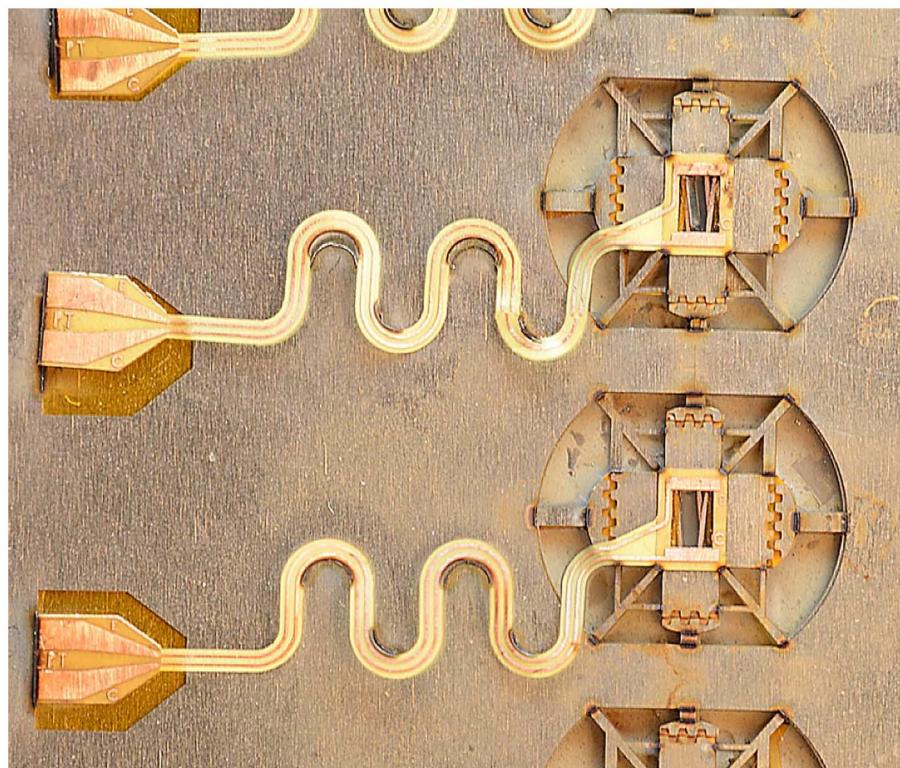
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Batch fabricated mm-scale force sensors, suitable for surgical robots, prior to release and self-assembly into the final 3D shape.

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## REVIEW ARTICLES

<i>Integrated Optics/Fiber Optical Devices</i>	
Optical Fiber Sensors in Physical Intrusion Detection Systems: A Review ....	G. Allwood, G. Wild, and S. Hinckley
	5497
<i>Sensors System Networks</i>	
Multi-Channel Surface Electromyography Electrodes: A Review .....	J. Kilby, K. Prasad, and G. Mawston
	5510

---

## SENSORS LETTERS

<i>Mechanical Sensors</i>	
Micromachined Frequency-Output Force Probes ....	M. Mahdavi, A. Abbasalipour, A. Ramezany, and S. Pourkamali
	5520
<i>Sensor Signal Processing and Array Sensor Fusion</i>	
Discussion on Maximum Likelihood-Based Methods for Inertial Sensor Calibration .....	S. Guerrier, R. Molinari, and J. Balamuta
	5522

---

## SENSORS PAPERS

<i>Sensor Materials and Solid-State Sensors</i>	
A Low-Power TDC-Configured Logarithmic Resistance Sensor for MLC PCM Readout .....	J.-W. Kwon, D.-H. Jin, H.-J. Kim, S.-I. Hwang, M.-C. Shin, J.-H. Cheon, and S.-T. Ryu
	5524
<i>Thermal Sensors</i>	
A Wide Range CMOS Temperature Sensor With Process Variation Compensation for On-Chip Monitoring .....	M. Jalalifar and G.-S. Byun
	5536
A Built-In Temperature Sensor in an Integrated Microheater .....	J.-W. Han and M. Meyyappan
	5543
<i>Magnetic Sensors</i>	
Nondestructive Testing of Back-Side Local Wall-Thinning by Means of Low Strength Magnetization and Highly Sensitive Magneto-Impedance Sensors .....	W. Cheng
	5548
Investigation of a Bending-Mode Magneto(Elasto)electric Sensor Using a Phase Modulation With a PLL .....	M.-T. Yang, X. Zhuang, M. Lam Chok Sing, C. Dolabdjian, D. Goldstein, P. Finkel, J. Li, and D. Viehland
	5557
<i>Microwave/Millimeter Wave Sensors</i>	
A Time-Based Angle-of-Arrival Sensor Using CMOS IR-UWB Transceivers .....	B. G. Yu, G. Lee, H. G. Han, W.-S. Ra, and T. W. Kim
	5563
W-Band Multichannel FMCW Radar Sensor With Switching-TX Antennas .....	S. Lee, J. Joo, J. Choi, W. Kim, H. Kwon, S. Lee, Y. Kwon, and J. Jeong
	5572
A Concept of Pressure Sensor Based on Slotted Waveguide Antenna Array for Passive MMID Sensor Networks ....	D. Hotte, R. Siragusa, Y. Duroc, and S. Tedjini
	5583

---

(Contents Continued on Page 5495)

<i><b>Ionizing Radiation Sensors</b></i>		
Wireless Sensing System for Flexible Arrayed Potentiometric Sensor Based on XBee Module .....	<i>J.-C. Chou, J.-T. Chen, Y.-H. Liao, C.-H. Lai, R.-T. Chen, Y.-L. Tsai, C.-Y. Lin, J.-S. Chen, M.-S. Huang, and H.-T. Chou</i>	5588
<i><b>Optoelectronic/Photonic Sensors</b></i>		
Comparison of Several Optical Methods for an Automated Fungal Spore Sensor System Concept .....	<i>R. Blank, P. Papireddy Vinayaka, M. W. Tahir, J. Yong, M. J. Vellekoop, and W. Lang</i>	5596
Lithium Niobate ( $\text{LiNbO}_3$ ) Waveguides for Electromagnetic Pulse (EMP) Sensing .....	<i>A. J. Waddie, A. Dzipalski, I. Thurston, M. Moutrie, and M. R. Taghizadeh</i>	5603
Advanced Photodetector Chip .....	<i>U. I. Oduah and Y. Wu</i>	5610
Role of Optimized Grooves Surface-Textured Front Glass in Improving $\text{TiO}_2$ Thin-Film UV Photodetector Performance .....	<i>H. Ferhati and F. Djeffal</i>	5618
<i><b>Integrated Optics/Fiber Optical Devices</b></i>		
Quality Detection of Alcoholic Beverages Using Optical Fiber Tips .....	<i>Y.-H. Tai, M.-Y. Pan, E.-H. Lin, D.-W. Huang, and P.-K. Wei</i>	5626
Multimode Interference-Based Fiber-Optic Ultrasonic Sensor for Non-Contact Displacement Measurement .....	<i>A. Sun, Z. Wu, D. Fang, J. Zhang, and W. Wang</i>	5632
<i><b>Sensor Phenomena and Characterization</b></i>		
Characterization of Acoustic Beam Propagation Through High-Grade Stainless Steel Pipes for Improved Pulsed Ultrasound Velocimetry Measurements in Complex Industrial Fluids .....	<i>T. J. Shamu, R. Kotzé, and J. Wiklund</i>	5636
<i><b>Sensor Signal Processing and Array Sensor Fusion</b></i>		
Shaping Radar Ambiguity Function by $L$ -Phase Unimodular Sequence .....	<i>J. Zhang, C. Shi, X. Qiu, and Y. Wu</i>	5648
Two-Dimensional Direction-of-Arrival Estimation for Co-Prime Planar Arrays: A Partial Spectral Search Approach .....	<i>Q. Wu, F. Sun, P. Lan, G. Ding, and X. Zhang</i>	5660
Moving Target Recognition Based on Transfer Learning and Three-Dimensional Over-Complete Dictionary .....	<i>Z. Yang, J. Deng, and A. Nallanathan</i>	5671
Magnetometer Calibration Using Inertial Sensors .....	<i>M. Kok and T. B. Schön</i>	5679
One-Decade Frequency Range, In-Phase Auto-Aligned 1.8 V 2 mW Fully Analog CMOS Integrated Lock-In Amplifier for Small/Noisy Signal Detection .....	<i>A. De Marcellis, G. Ferri, and A. D'Amico</i>	5690
Motion Artifact Cancellation of Seismocardiographic Recording From Moving Subjects .....	<i>C. Yang and N. Tavassolian</i>	5702
Transmit Beamspace Design for Multi-Carrier Frequency Diverse Array Sensor .....	<i>K. Gao, W.-Q. Wang, H. Chen, and J. Cai</i>	5709
<i><b>Sensor Systems</b></i>		
M2M Encountering: Collaborative Localization via Instant Inter-Particle Filter Data Fusion .....	<i>J.-W. Qiu and Y.-C. Tseng</i>	5715
Passive Wireless Frequency Doubling Antenna Sensor for Strain and Crack Sensing .....	<i>C. Cho, X. Yi, D. Li, Y. Wang, and M. M. Tentzeris</i>	5725
An Empirical Study for PCA- and LDA-Based Feature Reduction for Gas Identification .....	<i>M. A. Akbar, A. Ait Si Ali, A. Amira, F. Bensaali, M. Benammar, M. Hassan, and A. Bermak</i>	5734
Using Field Asymmetric Ion Mobility Spectrometry for Odor Assessment of Automobile Interior Components .....	<i>J. Li, R. Gutierrez-Osuna, R. D. Hodges, G. Luckey, J. Crowell, S. S. Schiffman, and H. T. Nagle</i>	5747
Activity Recognition With Smart Polymer Floor Sensor: Application to Human Footstep Recognition .....	<i>R. Serra, D. Knittel, P. Di Croce, and R. Peres</i>	5757
Biologically Inspired Feature Rank Codes for Hardware Friendly Gas Identification With the Array of Gas Sensors .....	<i>M. Hassan and A. Bermak</i>	5776
<i><b>Applications</b></i>		
Priority-Based Data Gathering Framework in UAV-Assisted Wireless Sensor Networks .....	<i>S. Say, H. Inata, J. Liu, and S. Shimamoto</i>	5785
Gas Source Parameter Estimation Using Machine Learning in WSNs .....	<i>S. Mahfouz, F. Mourad-Chehade, P. Honeine, J. Farah, and H. Snoussi</i>	5795

(Contents Continued from Page 5495)

---

Generation of Joint Trajectories Using Hybrid Automate-Based Model: A Rocking Block-Based Approach .....	V. B. Semwal and G. C. Nandi	5805
Guaranteed Cost Robust Weighted Measurement Fusion Kalman Estimators With Uncertain Noise Variances and Missing Measurements .....	C. Yang and Z. Deng	5817
<i>Sensors System Networks</i>		
Adaptive Relay Chain Routing With Load Balancing and High Energy Efficiency .....	L. Kong, K. Ma, B. Qiao, and X. Guo	5826
Self-Deployment of Mobile Sensors to Achieve Target Coverage in the Presence of Obstacles .....	M. Rout and R. Roy	5837

---