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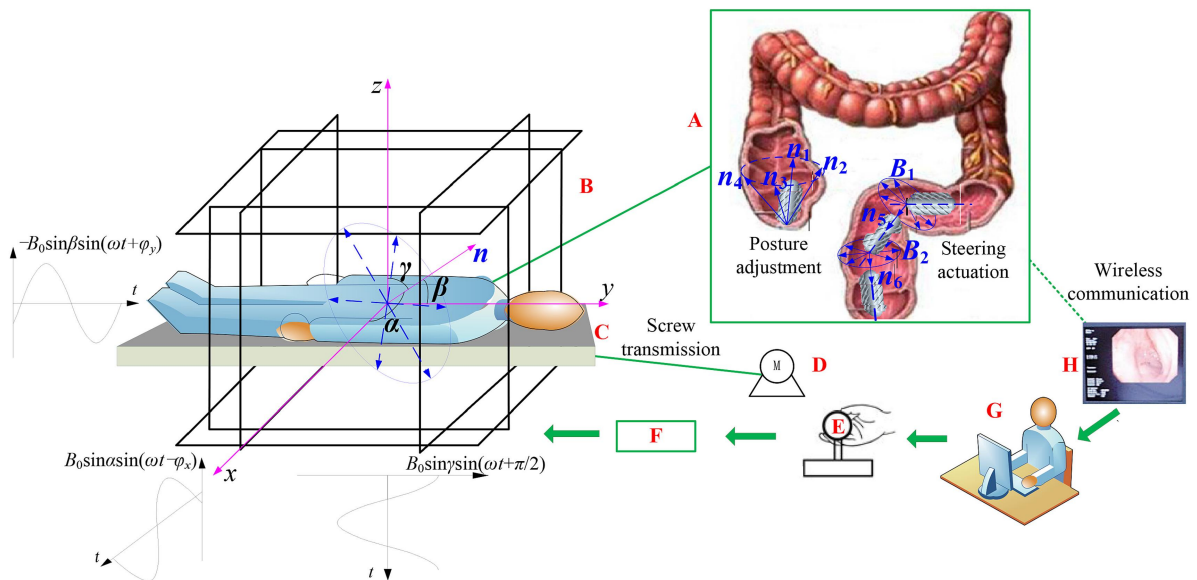
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PART II OF TWO PARTS



Application scenario of the petal-shaped capsule robot platform and the universal magnetic vector actuation system. From the paper, “Magnitude and Orientation Error Correction of a Superimposed Spatial Universal Rotating Magnetic Vector,” by Y. Zhang *et al.*, Art. no. 5100309.

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