

IEEE TRANSACTIONS ON **NEURAL SYSTEMS AND REHABILITATION ENGINEERING**

A PUBLICATION OF THE IEEE ENGINEERING IN MEDICINE AND BIOLOGY SOCIETY

The IEEE gratefully recognizes the technical co-sponsorship of RESNA and IFESS in the marketing and editing of this Transactions.



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AUGUST 2016

VOLUME 24

NUMBER 8

ITNSB3

(ISSN 1534-4320)



Experimental setup of Finger INdividuating Grasp Exercise Robot (FINGER), as described in the paper
“Movement Anticipation and EEG: Implications for BCI-Contingent Robot Therapy” by
S. L. Norman, M. Dennison, E. Wolbrecht, S. C. Cramer, R. Srinivasan, and D. J. Reinkensmeyer, on p. 911.

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